

EXOTIC DIFFERENTIAL STRUCTURES IN DIMENSION 2

SUNANDA DIKSHIT¹ AND DAVID GAULD²

ABSTRACT. It is known that the long line supports 2^{\aleph_1} many non-diffeomorphic differential structures. We show that the long plane supports a similar number of exotic differential structures, ie structures which are not merely diffeomorphic to the product of two structures on the factor spaces.

2010 *Mathematics Subject Classification*: 57R55, 57N05, 57R50

Keywords and Phrases: Long line, long ray, long plane, exotic differential structures, submanifold.

1. INTRODUCTION

In this paper, by a *differential structure* we mean a C^r differential structure for any $r \geq 1$. Recall, [3], that every C^r structure contains a C^s structure for any s satisfying $r < s \leq \infty$. Hence we are not concerned about the value of r .

It is well-known that euclidean space, \mathbb{R}^n , possesses a unique differential structure up to diffeomorphism for $n \neq 4$ but \mathbb{R}^4 has \mathfrak{c} mutually non-diffeomorphic differential structures; see [2, page 95] for early details and [5] for a recent survey. Thus \mathbb{R}^4 possesses many *exotic differential structures*, i.e., differential structures which are not diffeomorphic to the 4-fold product of \mathbb{R} with the usual structure (or the 2-fold product of \mathbb{R}^2 with the usual structure). Of course exotic differential structures were discovered more than half a century ago by Milnor in [4] where there is given the first construction of a differential structure on the 7-sphere \mathbb{S}^7 which is not diffeomorphic to the usual (product) differential structure inherited from \mathbb{R}^8 . The existence of two mutually non-diffeomorphic differential structures on a manifold is not possible for metrisable manifolds in dimension up to 3, [5]: this result is due to Radó in dimensions 1 and 2 and Moise in dimension 3.

On the other hand in [8] it is shown that when we relax the metrisability condition then even in dimension 1 there are 2^{\aleph_1} mutually non-diffeomorphic differential structures (on the long ray, hence also the long line \mathbb{L}). As a result there are also 2^{\aleph_1} mutually non-diffeomorphic differential structures on the long plane \mathbb{L}^2 . In this paper we address the question: does the long plane support differential structures which are not diffeomorphic to any product structure? Our answer is “yes.”

As usual we denote by ω_1 the set of countable ordinals with the order topology. Let $\mathbb{L}_{\geq 0}$ denote the *closed long ray*, ie the set $\omega_1 \times [0, 1)$ with the lexicographic order topology, and let \mathbb{L} denote the *long line* which is obtained from two copies of the closed long ray with their initial points identified to 0. The *(open) long ray* is the 1-manifold $\mathbb{L}_+ = \mathbb{L}_{\geq 0} - \{(0, 0)\}$. Identify $\alpha \in \omega_1$ with $(\alpha, 0) \in \mathbb{L}_{\geq 0}$. We will exhibit non-product differential structures on \mathbb{L}_+^2 . As in [8] similar structures may then be deduced on \mathbb{L}^2 .

The following result is well-known and is found in many books introducing Set Theory but we include it for completeness. Note that it does not matter whether we are considering C and D as subsets of ω_1 or \mathbb{L}_+ .

Date: November 22, 2012.

^{1,2}Supported in part by a grant from the New Zealand Institute of Mathematics and its Applications. This work represents part of the first author’s PhD thesis prepared at the University of Auckland under the supervision of the second author.

Lemma 1. *If $C, D \subset \omega_1$ are closed unbounded subsets then $C \cap D$ is also closed and unbounded.*

Proposition 2. *Suppose that \mathcal{D} is a differential structure on \mathbb{L}_+ and $\alpha \in \mathbb{L}_+$. Then $((\alpha, \omega_1), \mathcal{D}|(\alpha, \omega_1))$ is diffeomorphic to $(\mathbb{L}_+, \mathcal{D})$.*

Proof. Choose $\beta, \gamma \in \mathbb{L}_+$ such that $\alpha < \beta < \gamma$. Because \mathbb{R} has a unique differential structure up to diffeomorphism and $(0, \gamma) \subset \mathbb{L}_+$ is homeomorphic to \mathbb{R} we may choose a diffeomorphism $g : ((0, \gamma), \mathcal{D}|(0, \gamma)) \rightarrow ((0, 3), \mathcal{U})$, where \mathcal{U} is the usual differential structure on \mathbb{R} restricted to $(0, 3)$. Furthermore we may assume that $g(\alpha) = 1$ and $g(\beta) = 2$. Next let $\theta : (0, 3) \rightarrow (1, 3)$ be a diffeomorphism (relative to \mathcal{U}) such that $\theta(t) = t$ for all $t \in [2, 3]$. For example set $\theta(t) = \begin{cases} t + \sqrt{e}e^{\frac{1}{t-2}} & \text{if } t < 2 \\ t & \text{if } t \geq 2 \end{cases}$. Now define $h : \mathbb{L}_+ \rightarrow (\alpha, \omega_1)$ by $h(t) = \begin{cases} g^{-1}\theta g(t) & \text{if } t < \gamma \\ t & \text{if } t > \beta \end{cases}$. Then h is a diffeomorphism with respect to the structure \mathcal{D} . \square

Recall the following result from [1, Corollary 2.6].

Proposition 3. *Suppose that $h : \mathbb{L}_+^2 \rightarrow \mathbb{L}_+^2$ is an orientation-preserving homeomorphism. Then $\{\alpha \in \omega_1 / h(\mathbb{L}_+ \times \{\alpha\}) = \mathbb{L}_+ \times \{\alpha\}\}$ is a closed unbounded set.*

Corollary 4. *Suppose that \mathcal{F} is a differential structure on \mathbb{L}_+^2 and that \mathcal{F} is diffeomorphic to the product of two structures. Then*

$$\{\alpha \in \omega_1 / \mathbb{L}_+ \times \{\alpha\} \text{ is a differentiable submanifold of } (\mathbb{L}_+^2, \mathcal{F})\}$$

and

$$\{\alpha \in \omega_1 / \{\alpha\} \times \mathbb{L}_+ \text{ is a differentiable submanifold of } (\mathbb{L}_+^2, \mathcal{F})\}$$

are closed unbounded subsets of ω_1 .

Proof. There are two differential structures, say \mathcal{D}, \mathcal{E} , on \mathbb{L}_+ and a diffeomorphism $h : (\mathbb{L}_+, \mathcal{D}) \times (\mathbb{L}_+, \mathcal{E}) \rightarrow (\mathbb{L}_+^2, \mathcal{F})$. Interchanging the roles of \mathcal{D} and \mathcal{E} if necessary we may assume h preserves orientation. By Proposition 3, $S = \{\alpha \in \omega_1 / h(\mathbb{L}_+ \times \{\alpha\}) = \mathbb{L}_+ \times \{\alpha\}\}$ is a closed unbounded set. Thus $\mathbb{L}_+ \times \{\alpha\}$ is a differentiable submanifold of $(\mathbb{L}_+^2, \mathcal{F})$ for each $\alpha \in S$. Interchanging the coordinates leads to the other half. \square

We also require the following folklore result, cf [7, Theorem 1] and [6, Theorem 3 page 46].

Proposition 5. *Let $M \subset \mathbb{R}^2$ be a compact topological manifold with boundary, $K \subset M$ a compact subset which contains the boundary of M and suppose that $h : M \rightarrow M$ is a homeomorphism which is a diffeomorphism on a neighbourhood of K . Then h can be approximated arbitrarily closely by a homeomorphism which is a diffeomorphism on $\overset{\circ}{M}$ and agrees with h on a neighbourhood of K .*

2. EXOTIC DIFFERENTIAL STRUCTURES ON \mathbb{L}_+^2

We now present a method of constructing from two differential structures on the long ray a differential structure on \mathbb{L}_+^2 which is not diffeomorphic to the product of any two differential structures on \mathbb{L}_+ . The construction allows us to verify that there are 2^{\aleph_1} many non-diffeomorphic such structures.

We require an auxiliary shearing homeomorphism $\sigma : [0, 5]^2 \rightarrow [0, 5]^2$. The homeomorphism σ is the identity except in the rectangle $(3, 4) \times (1, 4)$, does not change the first coordinate and maps the straight line segment $[3, 4] \times \{2\}$ onto the two line segments $\{(x, 3 - 2|x - 3\frac{1}{2}|) : 3 \leq x \leq 4\}$. The notation $I_\alpha = (0, \alpha + 1)$, $\overline{I}_\alpha = [0, \alpha + 1]$, $O_\alpha = I_\alpha^2 \subset \mathbb{L}_+^2$ and $\overline{O}_\alpha = \overline{I}_\alpha^2 \subset \mathbb{L}_{\geq 0}^2$ is fixed throughout this section.

Begin with two differential structures \mathcal{D} and \mathcal{E} on \mathbb{L}_+ ; for example any of those in [8] will do. For each $\alpha \in \omega_1 \setminus \{0\}$ choose order-preserving homeomorphisms $\psi_\alpha, \chi_\alpha : \overline{I_\alpha} \rightarrow [0, 5]$ so that $\psi_\alpha(\alpha) = \chi_\alpha(\alpha) = 2$, and that $(I_\alpha, \psi_\alpha) \in \mathcal{D}$ and $(I_\alpha, \chi_\alpha) \in \mathcal{E}$.

For each $\alpha \in \omega_1 \setminus \{0\}$ we will construct by induction on α a homeomorphism $\varphi_\alpha : \overline{O_\alpha} \rightarrow [0, 5]^2$ in such a way that $\{(O_\alpha, \varphi_\alpha) \mid \alpha \in \omega_1 \setminus \{0\}\}$ is a basis for a differential structure on \mathbb{L}_+^2 , i.e., for each $\alpha, \beta \in \omega_1 \setminus \{0\}$ the maps $\varphi_\alpha \varphi_\beta^{-1}$ and $\varphi_\beta \varphi_\alpha^{-1}$ are smooth where defined within $(0, 5)^2$. The induction includes the further condition:

- The homeomorphisms $\psi_\alpha \times \chi_\alpha$ and φ_α agree on neighbourhoods of $\overline{O_\alpha} \setminus O_\alpha$ and of $[0, \alpha) \times [\alpha, \alpha + 1]$ as well as on a neighbourhood in $\overline{O_\alpha} \setminus [0, \alpha)^2$ of $\{\alpha\} \times [0, \alpha]$.

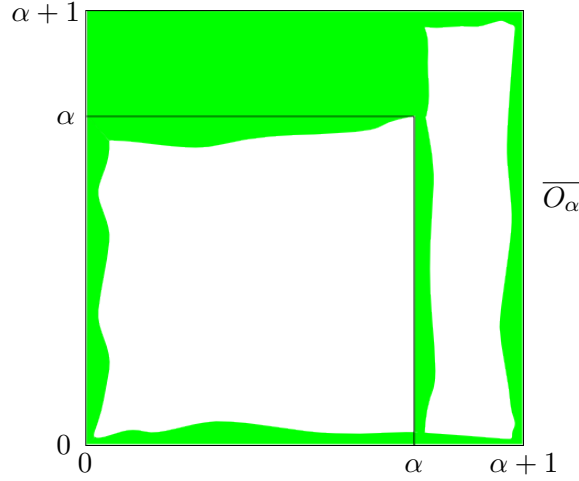


FIGURE 1. Where $\varphi_\alpha = \psi_\alpha \times \chi_\alpha$.

Definition of φ_1 : Set $\varphi_1 = \sigma(\psi_1 \times \chi_1)$.

Definition of $\varphi_{\alpha+1}$ given φ_α : Define

$$\varphi_{\alpha+1}(z) = \begin{cases} (\psi_{\alpha+1} \times \chi_{\alpha+1})(\psi_\alpha \times \chi_\alpha)^{-1} \varphi_\alpha(z) & \text{if } z \in \overline{O_\alpha}; \\ \sigma(\psi_{\alpha+1} \times \chi_{\alpha+1})(z) & \text{if } z \in \overline{O_{\alpha+1}} - O_\alpha. \end{cases}$$

It is easily checked that the inductive conditions are satisfied.

Definition of φ_α , where α is a limit ordinal, given φ_β for all $\beta \in \omega_1 \setminus \{0\}$ with $\beta < \alpha$: Firstly choose some metric d on $\overline{O_\alpha}$ compatible with the topology. Next choose an increasing sequence $\langle \alpha_n \rangle$ from $\omega_1 \setminus \{0\}$ converging to α ; set $\alpha_0 = 0$. Somewhat as in the previous case we would like to let φ_α be $(\psi_\alpha \times \chi_\alpha)(\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1} \varphi_{\alpha_n}$ on $\overline{O_{\alpha_n}}$ and be $\sigma(\psi_\alpha \times \chi_\alpha)$ outside the union of these common domains but this would work only if all maps of the form $(\psi_{\alpha_m} \times \chi_{\alpha_m})^{-1} \varphi_{\alpha_m}$ and $(\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1} \varphi_{\alpha_n}$ agree on $\overline{O_{\min\{m,n\}}}$. We modify these maps inductively so that they do agree, at least on enough of $\overline{O_{\min\{m,n\}}}$. To effect this we construct a sequence of homeomorphisms $\langle h_n : [0, 3]^2 \rightarrow [0, 3]^2 \rangle$, where $n \geq 1$. We demand the following properties:

- $h_n : (0, 3)^2 \rightarrow (0, 3)^2$ is a diffeomorphism;
- h_n is the identity on a neighbourhood of $([0, 3] \times [2, 3]) \cup ([2, 3] \times [0, 3])$;
- $h_n = (\psi_{\alpha_n} \times \chi_{\alpha_n})(\psi_{\alpha_{n-1}} \times \chi_{\alpha_{n-1}})^{-1} h_{n-1} \varphi_{\alpha_{n-1}} \varphi_{\alpha_n}^{-1}$ on a neighbourhood of $\varphi_{\alpha_n}([0, \alpha_{n-1})^2)$ when $n > 1$;
- $h_n = (\psi_{\alpha_n} \times \chi_{\alpha_n}) \varphi_{\alpha_n}^{-1}$ on a neighbourhood of $\varphi_{\alpha_n}([0, \alpha_{n-1}) \times [\alpha_{n-1}, \alpha_n])$ when $n > 1$;

- for $n > 1$, on $\varphi_{\alpha_n}([\alpha_{n-1}, \alpha_n] \times [0, \alpha_{n-2}])$, h_n is sufficiently close to $(\psi_{\alpha_n} \times \chi_{\alpha_n})\varphi_{\alpha_n}^{-1}$ that for any $(x, y) \in \varphi_{\alpha_n}([\alpha_{n-1}, \alpha_n] \times [0, \alpha_{n-2}])$, we have

$$d((\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1}(x, y), (\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1}h_n(x, y)) < \frac{1}{n}.$$

To achieve this we use uniform continuity of $(\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1}$.

Notice that the conditions on h_n are mutually consistent by the inductively assumed conditions on φ_{α_m} and h_{n-1} .

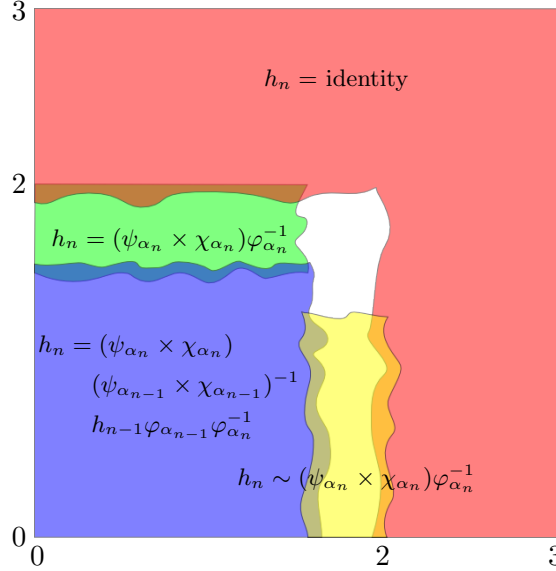


FIGURE 2. Constraints on h_n .

Let $h_1 : [0, 3]^2 \rightarrow [0, 3]^2$ be the identity. Suppose given $n > 1$ such that h_{n-1} has been defined. By Proposition 5 there is a homeomorphism $h_n : [0, 3]^2 \rightarrow [0, 3]^2$ satisfying the requirements.

Now define φ_α by

$$\varphi_\alpha(x) = \begin{cases} (\psi_\alpha \times \chi_\alpha)(\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1}h_n\varphi_{\alpha_n}(x) & \text{if } x \in [0, \alpha_n]^2 \text{ for some } n \\ \sigma(\psi_\alpha \times \chi_\alpha)(x) & \text{if } x \in O_\alpha \setminus (0, \alpha)^2 \end{cases}.$$

The function φ_α is well-defined because if $m < n$ then $(\psi_{\alpha_m} \times \chi_{\alpha_m})^{-1}h_m\varphi_{\alpha_m}$ and $(\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1}h_n\varphi_{\alpha_n}$ agree on $[0, \alpha_m]^2$. It is easily verified that φ_α is a homeomorphism, the main problem being to verify continuity on $\{\alpha\} \times [0, \alpha]$. It is here that we require precision in the approximation of the homeomorphism $(\psi_{\alpha_n} \times \chi_{\alpha_n})\varphi_{\alpha_n}^{-1}$ by the diffeomorphism as required in the last inductive assumption for h_n . The approximation must improve as n increases so that any sequence $\langle (x_n, y_n) \rangle$ in $[0, \alpha]^2$ converging to $(\alpha, y) \in \{\alpha\} \times [0, \alpha]$ is mapped by $(\psi_{\alpha_m} \times \chi_{\alpha_m})^{-1}h_m\varphi_{\alpha_m}$ (m increasing with n) to a sequence which also converges to (α, y) . Then $\varphi_\alpha(x_n, y_n) \rightarrow (\psi_\alpha \times \chi_\alpha)(\alpha, y) = \varphi(\alpha, y)$ as σ is the identity on $\{2\} \times [0, 5]$.

Suppose $\beta < \alpha$. Then the coordinate transformation between φ_α and φ_β is smooth on $\varphi_\beta(O_{\beta+1})$ because

$$\varphi_\alpha\varphi_\beta^{-1} = (\psi_\alpha \times \chi_\alpha)(\psi_{\alpha_n} \times \chi_{\alpha_n})^{-1}h_n\varphi_{\alpha_n}\varphi_\beta^{-1}$$

is a composition of coordinate transition functions together with the diffeomorphism h_n and hence is smooth, where n is chosen so that $\alpha_n > \beta$. Similarly its inverse is smooth.

The remaining condition demanded of φ_α is also satisfied.

Thus we have constructed a basis $\{(O_\alpha, \varphi_\alpha) \mid \alpha \in \omega_1 \setminus \{0\}\}$ for a differential structure on \mathbb{L}_+^2 . Call this structure \mathcal{F} .

Claim 6. *The differential structure \mathcal{F} is not diffeomorphic to a product of structures on \mathbb{L}_+ .*

Proof. Let $\alpha < \omega_1$ be any non-zero ordinal. We first show that $\mathbb{L}_+ \times \{\alpha\}$ is not a smooth submanifold of $(\mathbb{L}_+^2, \mathcal{F})$. Suppose instead that $\mathbb{L}_+ \times \{\alpha\}$ is a smooth submanifold of $(\mathbb{L}_+^2, \mathcal{F})$. Then $(\alpha, \alpha+1) \times \{\alpha\}$ is also a smooth submanifold of $(\mathbb{L}_+^2, \mathcal{F})$, so there is a chart $((\alpha, \alpha+1) \times (0, \alpha+1), \varphi) \in \mathcal{F}$ such that $\varphi^{-1}(\mathbb{R} \times \{0\}) = (\alpha, \alpha+1) \times \{\alpha\}$. It follows that $\varphi_\alpha \varphi^{-1}(\mathbb{R} \times \{0\}) = \varphi_\alpha((\alpha, \alpha+1) \times \{\alpha\})$ is a smooth submanifold of \mathbb{R}^2 with the usual differential structure. However, for $t \in (\alpha, \alpha+1)$ we have $\varphi_\alpha(t, \alpha) = \sigma(\psi_\alpha(t), 2)$, and hence

$$\varphi_\alpha((\alpha, \alpha+1) \times \{\alpha\}) = ((2, 3] \cup [4, 5)) \times \{2\} \cup \left\{ \left(x, 3 - 2 \left\lfloor x - 3\frac{1}{2} \right\rfloor \right) : 3 \leq x \leq 4 \right\}.$$

As this last set is not a smooth submanifold of \mathbb{R}^2 , it follows that $(0, \omega_1) \times \{\alpha\}$ is not a smooth submanifold of $(\mathbb{L}_+^2, \mathcal{F})$.

The claim now follows from Lemma 1 and Corollary 4 because $\omega_1 \setminus \{0\}$ is closed and unbounded. \square

We now address the question: how many exotic differential structures does \mathbb{L}_+^2 support? The argument presented in [8, p.156] that \mathbb{L}_+ supports no more than 2^{\aleph_1} many mutually non-diffeomorphic differential structures applies as well to \mathbb{L}_+^2 . On the other hand [8, Theorem 5.2] exhibits exactly 2^{\aleph_1} many mutually non-diffeomorphic differential structures on \mathbb{L}_+ . Thus we might expect to find 2^{\aleph_1} many mutually non-diffeomorphic exotic differential structures on \mathbb{L}_+^2 , and this is indeed the case.

Let \mathcal{D} be any differential structure on \mathbb{L}_+ . Apply the construction above with $\mathcal{E} = \mathcal{D}$ and denote the resulting exotic differential structure on \mathbb{L}_+^2 by $\widehat{\mathcal{D}}$.

Theorem 7. *There are 2^{\aleph_1} mutually non-diffeomorphic exotic differential structures on \mathbb{L}_+^2 .*

Proof. Suppose given differential structures \mathcal{D} and \mathcal{E} on \mathbb{L}_+ and an orientation-preserving diffeomorphism $h : (\mathbb{L}_+^2, \widehat{\mathcal{D}}) \rightarrow (\mathbb{L}_+^2, \widehat{\mathcal{E}})$. By Proposition 3, for a closed unbounded set of $\alpha \in \omega_1$, the map h restricts to a homeomorphism taking $\{\alpha\} \times (\alpha, \omega_1)$ to itself. Now $\widehat{\mathcal{D}}|_{\{\alpha\} \times (\alpha, \omega_1)}$ is the same as $\mathcal{D} \times \mathcal{D}|_{\{\alpha\} \times (\alpha, \omega_1)}$ with the same for \mathcal{E} so, using Proposition 2 and denoting “is diffeomorphic to” by \approx , we have

$$\begin{aligned} (\mathbb{L}_+, \mathcal{D}) &\approx ((\alpha, \omega_1), \mathcal{D}) \\ &\approx (\{\alpha\} \times (\alpha, \omega_1), \mathcal{D} \times \mathcal{D}|_{\{\alpha\} \times (\alpha, \omega_1)}) \\ &\approx (\{\alpha\} \times (\alpha, \omega_1), \widehat{\mathcal{D}}|_{\{\alpha\} \times (\alpha, \omega_1)}) \\ &\approx (\{\alpha\} \times (\alpha, \omega_1), \widehat{\mathcal{E}}|_{\{\alpha\} \times (\alpha, \omega_1)}) \\ &\approx (\{\alpha\} \times (\alpha, \omega_1), \mathcal{E} \times \mathcal{E}|_{\{\alpha\} \times (\alpha, \omega_1)}) \\ &\approx ((\alpha, \omega_1), \mathcal{E}) \\ &\approx (\mathbb{L}_+, \mathcal{E}). \end{aligned}$$

It follows that for any differential structure \mathcal{D} on \mathbb{L}_+ there can be at most one equivalence class of structures, represented say by \mathcal{E} , such that $(\mathbb{L}_+^2, \widehat{\mathcal{D}})$ is diffeomorphic to $(\mathbb{L}_+^2, \widehat{\mathcal{E}})$ but $(\mathbb{L}_+, \mathcal{D})$ is not diffeomorphic to $(\mathbb{L}_+, \mathcal{E})$. Indeed, if \mathcal{D} , \mathcal{E} and \mathcal{F} are three differential structures on \mathbb{L}_+ and $(\mathbb{L}_+^2, \widehat{\mathcal{D}})$ is diffeomorphic to both $(\mathbb{L}_+^2, \widehat{\mathcal{E}})$ and $(\mathbb{L}_+^2, \widehat{\mathcal{F}})$ but $(\mathbb{L}_+, \mathcal{D})$ is not diffeomorphic to either $(\mathbb{L}_+, \mathcal{E})$ or $(\mathbb{L}_+, \mathcal{F})$, then diffeomorphisms $g : (\mathbb{L}_+^2, \widehat{\mathcal{D}}) \rightarrow (\mathbb{L}_+^2, \widehat{\mathcal{E}})$ and $h : (\mathbb{L}_+^2, \widehat{\mathcal{D}}) \rightarrow (\mathbb{L}_+^2, \widehat{\mathcal{F}})$ must reverse

orientation. In that case the diffeomorphism $hg^{-1} : (\mathbb{L}_+^2, \widehat{\mathcal{E}}) \rightarrow (\mathbb{L}_+^2, \widehat{\mathcal{F}})$ preserves orientation and hence $(\mathbb{L}_+, \mathcal{E})$ is diffeomorphic to $(\mathbb{L}_+, \mathcal{F})$ by what we have already shown.

It now follows from [8, Theorem 5.2] that there are 2^{\aleph_1} mutually non-diffeomorphic exotic differential structures on \mathbb{L}_+^2 . \square

As a complement to Theorem 7 we have the following.

Theorem 8. *There are 2^{\aleph_1} mutually non-diffeomorphic product differential structures on \mathbb{L}_+^2 .*

Proof. It suffices to show that if \mathcal{D} and \mathcal{E} are two differential structures on \mathbb{L} such that $(\mathbb{L}^2, \mathcal{D} \times \mathcal{D})$ is diffeomorphic to $(\mathbb{L}^2, \mathcal{E} \times \mathcal{E})$ then $(\mathbb{L}, \mathcal{D})$ is diffeomorphic to $(\mathbb{L}, \mathcal{E})$. However it is easy to show that the homeomorphism $(x, x) \mapsto x$ from the diagonal Δ of \mathbb{L}^2 to \mathbb{L} is a diffeomorphism from $(\Delta, \mathcal{D} \times \mathcal{D}|_{\Delta})$ to $(\mathbb{L}, \mathcal{D})$. \square

REFERENCES

- [1] Mathieu Baillif, Satya Deo and David Gauld *The mapping class group of powers of the long ray and other non-metrisable spaces*, Topology Appl., 157(2010), 1314–1324.
- [2] Robion C. Kirby, *The topology of 4-manifolds*, Lecture Notes in Mathematics 1374, Springer-Verlag, Berlin, Heidelberg, New York, London, Paris, Tokyo, Hong Kong (1989).
- [3] Winfried Koch and Dieter Puppe, *Differenzierbare Strukturen auf Mannigfaltigkeiten ohne abzählbare Basis*, Arch. Math. (Basel), 19(1968), 95–102.
- [4] John Milnor, *On manifolds homeomorphic to the 7-sphere*, Ann. of Math., (2) 64(1956), 399–405.
- [5] John Milnor, *Differential Topology Forty-six Years Later*, Notices Amer. Math. Soc., 58(2011), 804–809.
- [6] Edwin E. Moise, *Geometric topology in dimensions 2 and 3*, Springer-Verlag, New York, Heidelberg, Berlin (1977).
- [7] James Munkres, *Obstructions to extending diffeomorphisms*, Proc. Amer. Math. Soc., 15(1964), 297–299.
- [8] Peter Nyikos, *Various smoothings of the long line and their tangent bundles*, Adv. Math., 93(1992), no. 2, 129–213.

¹ DEPARTMENT OF MATHEMATICS, THE UNIVERSITY OF AUCKLAND, PRIVATE BAG 92019, AUCKLAND, NEW ZEALAND

E-mail address: s.dixit@math.auckland.ac.nz

²DEPARTMENT OF MATHEMATICS, THE UNIVERSITY OF AUCKLAND, PRIVATE BAG 92019, AUCKLAND, NEW ZEALAND

E-mail address: d.gauld@auckland.ac.nz